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QUICK REVISION

FORMULA SHEET

for

GATE-AE FLUID MECHANIC





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FLUID MECHANICS

FLUID BASICS

Note:

1. For a static fluid, shear force is zero.
2. Fluids only show resistance to compressive loads.

$$k = \text{Bulk Modulus} = \frac{\text{Hydro static stress}}{\text{Volumetric strain}} = \frac{-dp}{dV/V}$$

$$\beta = \frac{1}{k}$$

(β) = Compressibility

For Incompressible fluid $\beta = 0$

Reason of viscosity(μ) in liquids $\rightarrow$ Cohesive force (Molecular Bonding)

Reason of viscosity(μ) in gases $\rightarrow$ Molecular Collision.

- Temperature $\uparrow \Rightarrow \mu_{\text{liquid}} \downarrow \Rightarrow \nu_{\text{liquid}} \downarrow$
Where $\nu_{\text{liquid}} \Rightarrow$ Kinematic viscosity of liquid.
- Temperature $\uparrow \Rightarrow \mu_{\text{gas}} \uparrow \Rightarrow \nu_{\text{gas}} \uparrow \uparrow$
- Pressure $\uparrow \Rightarrow \mu_{\text{liquid}}$: same $\Rightarrow \nu_{\text{liquid}}$: same
- Pressure $\uparrow \Rightarrow \mu_{\text{gas}}$: same $\Rightarrow \nu_{\text{liquid}}$: $\downarrow$

Newton's Law of Viscosity:

$$\tau = \mu \frac{du}{dy} \quad \tau = \text{shear stress}$$

where μ = Viscosity/Dynamic viscosity

Unit of $\mu \rightarrow$ kg/(meter-sec) or pascal-sec

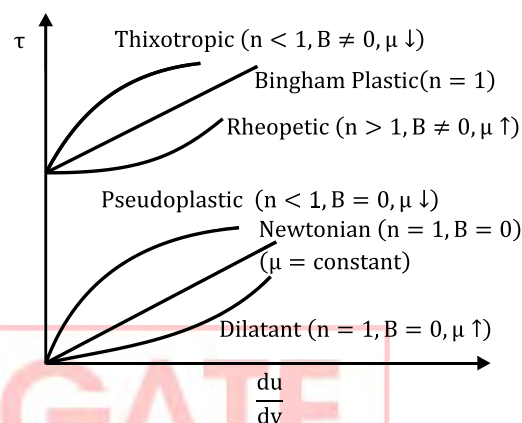
$$\frac{1\text{kg}}{\text{meter-sec}} = 10 \text{ poise}$$

$$1\text{poise} = 0.1\text{pascal-sec}$$

Kinematic viscosity (ν) = meter²/sec

$$\frac{1\text{m}^2}{\text{sec}} = 10^4 \text{ stokes}$$

Stokes Cgs unit of kinematic viscosity



For Non-Newtonian Fluid:

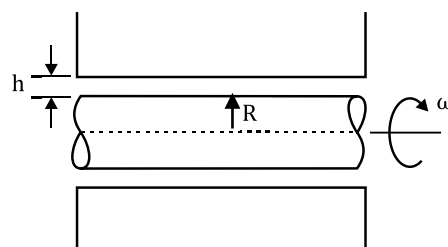
$$\tau = A \left(\frac{du}{dy} \right)^n + B$$

Ideal Fluid:

- Non viscous
- Incompressible

Power Lost in Bearing due to Fluid Friction:

Case 1:



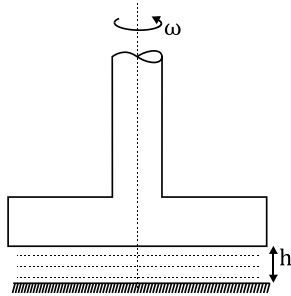
$$\text{Power} = \frac{2\pi\mu\omega^2LR^3}{h}$$

R = Radius of shaft

h = oil film gap

ω = angular velocity of shaft

Case 2:



$$\text{Torque} = \frac{\pi \mu \omega R^4}{2h}$$

FLUID STATICS

$$p_{\text{absolute}} = p_{\text{atm}} + p_{\text{gauge}}$$

Hydrostatic Law:



$$\frac{dp}{dh} = -\rho g$$

Hydrostatic Forces:

$$F = \rho g \bar{h} A$$

$\bar{h}$ = Distance of centre of gravity from free liquid surface.

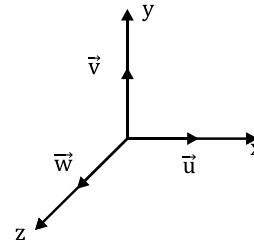
Location of hydrostatic forces

$$\bar{h}_{cp} = \bar{h} + \frac{I_{Gx} \sin^2 \theta}{A \bar{h}}$$

$\bar{h}_{cp}$ = Distance of pressure force from free liquid surface.

FLUID KINEMATICS

Acceleration:



$$\mathbf{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$$

$$a_x = u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} + \frac{\partial u}{\partial t}$$

$$a_y = u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} + \frac{\partial v}{\partial t}$$

$$a_z = u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} + \frac{\partial w}{\partial t}$$

$$\frac{\partial u}{\partial t}, \frac{\partial v}{\partial t}, \frac{\partial w}{\partial t}$$

These are local component or temporal component of acceleration.

$$\vec{a} = \vec{a}_{\text{convective}} + \vec{a}_{\text{temporal}}$$

Angular Velocity:

$$\vec{V} = u\hat{i} + v\hat{j} + w\hat{k}$$

$$\omega = \frac{1}{2} (\nabla \times \vec{V})$$

$$\omega_x = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right)$$

$$\omega_y = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right)$$

$$\omega_z = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

$$\text{Vorticity } (\Omega) = \nabla \times \vec{V} = 2\vec{\omega}$$

Linear strain rate:

$$\epsilon_{xx} = \frac{\partial u}{\partial x}, \epsilon_{yy} = \frac{\partial v}{\partial y}, \epsilon_{zz} = \frac{\partial w}{\partial z}$$

$$\epsilon_v = \epsilon_{xx} + \epsilon_{yy} + \epsilon_{zz}$$

(Volumetric strain rate) or Dilation

$\varepsilon_v = 0$ For incompressible flow

Shear Strain Rate:

$$\varepsilon_{xy} = \frac{1}{2} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)$$

$$\varepsilon_{xz} = \frac{1}{2} \left(\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right)$$

$$\varepsilon_{yz} = \frac{1}{2} \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)$$

u = x component of velocity

v = y component of velocity

w = z componet of velocity

Shear deformation rate / Angular deformation rate:

$$\gamma_{xy} = \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]$$

Circular (Γ):

$$\Gamma = \int \vec{V} \cdot d\vec{r} \quad (\text{or}) \quad \Omega \times \text{Area (or)} \iint \Omega dA$$

Ω = Vorticity

Velocity Potential Function (ϕ) for 3D flow.

$$u = \frac{\partial \phi}{\partial x}$$

$$v = \frac{\partial \phi}{\partial y}$$

$$w = \frac{\partial \phi}{\partial z}$$

In Polar coordinator:

$$u_r = \frac{\partial \phi}{\partial r}$$

$$V_\theta = + \frac{1}{r} \frac{\partial \phi}{\partial \theta}$$

- If ϕ exists $\Rightarrow$ Flow is irrotational

- If ϕ satisfies Laplace equation $\Rightarrow$ Flow is possible.

- Slope of equipotential line

$$\Rightarrow -\frac{u}{v} \Rightarrow \frac{dy}{dx}$$

Stream Function (ψ) (For 2D Flow):

$$u = \frac{\partial \psi}{\partial y}$$

$$v = -\frac{\partial \psi}{\partial x}$$

$$u_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta}$$

$$V_\theta = -\frac{\partial \psi}{\partial r}$$

- If ψ exists $\Rightarrow$ Flow is possible
- If ψ satisfied Laplace equation $\Rightarrow$ Flow is irrotational
- Slope of streamline
 $\Rightarrow \frac{dy}{dx} = \frac{v}{u}$

Laplace Equation:

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$$

$$\nabla^2 \phi = 0$$

$$\nabla^2 (\text{any variable}) = 0 \quad (\text{Laplace Equation})$$

$$\text{Discharge Per unit length} = |\psi_1 - \psi_2|$$

FLUID DYNAMICS

$F_{\text{pressure}}, F_{\text{gravity}}, F_{\text{viscous}}$

$\Rightarrow$ Use Navier-strokes equation

$F_{\text{pressure}}, F_{\text{gravity}} \Rightarrow$ Euler equation

$F_{\text{pressure}}, F_{\text{gravity}}$ and incompressible
 $\Rightarrow$ Bernoulli's equation

Ideal Bernoulli's Equation: (Can be used for rotational flow also but Flow must be along same streamline)

$$\frac{p}{\rho g} + \frac{V^2}{2g} + z = \text{Constant}$$

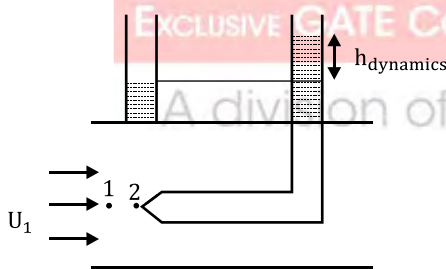
Assumptions:

- Non viscous
- Steady flow
- Incompressible flow of incompressible fluid
- Irrotational flow.

For Practical use (Bernoulli's equation with losses)

$$\frac{p_1}{\rho g} + \frac{V_1^2}{2g} + Z_1 = \frac{p_2}{\rho g} + \frac{V_2^2}{2g} + Z_2 + h_{\text{losses}}$$

Pitot Tube: (Measures stagnation pressure head).



$$u_1 = \sqrt{2g h_{\text{dynamic}}}$$

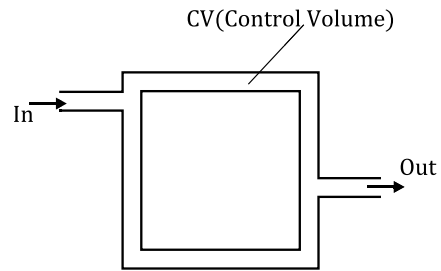
$$h_{\text{dynamic}} = x \left(\frac{\rho_m}{\rho} - 1 \right)$$

x = Manometric deflection

(or)

$$h = \left(\frac{p_2}{\rho g} + Z_2 \right) - \left(\frac{p_1}{\rho g} + Z_1 \right)$$

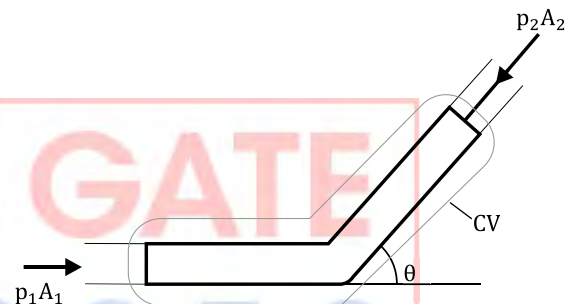
Impulse Momentum Equation:



$$\vec{F}_{\text{net}} + \sum \dot{m}_i \vec{v}_i = \left(\frac{d(mv)}{dt} \right)_{\text{cv}} + \sum \dot{m}_o \vec{v}_o$$

$$f_{\text{net}} = \dot{m}_o V_o - \dot{m}_i v_i \quad (\text{for steady flow})$$

If pressure forces considered, then



$$F_x + p_1 A_1 - p_2 A_2 \cos \theta = \dot{m} [V_2 \cos \theta - V_1]$$

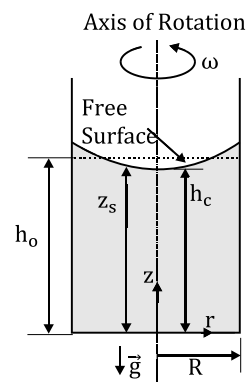
$$F_y - p_2 A_2 \sin \theta = \dot{m} [V_2 \sin \theta]$$

f_{net} or $F_x, F_y \rightarrow$ Force exerted by pipe bend or structure on fluid element.

Rotational flow in a Cylindrical Container:

Equation of motion for vortex flow

$$dP = \rho \omega^2 dr - \rho g dz$$

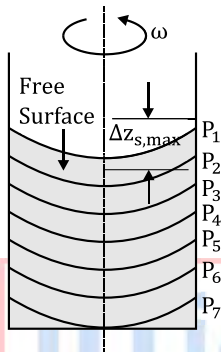


the equation of the free surface

$$z_s = h_0 - \frac{\omega^2}{4g} (R^2 - 2r^2)$$

The maximum vertical height occurs at the edge where $r = R$, and the maximum height difference between the edge and the center of the free surface is

$$\Delta z_{s,\max} = z_s(R) - z_s(0) = \frac{\omega^2}{2g} R^2$$



where h_0 is the original height of the fluid in the container with no rotation

FLUID THROUGH PIPES

Darcy Weisbeck Equation:

$$h_f = \frac{fLV^2}{2gd} \quad \text{Valid for Laminar and Turbulent}$$

$$f = \text{Friction factor} = \frac{64}{Re} \quad \text{Laminar flow}$$

$$Re = \text{Reynolds Number} = \frac{\rho V D_H}{\mu}$$

P_H = Hydraulic diameter

Laminar Flow:

1. **Through Pipe:**

$$(A) \tau = -\frac{r}{2} \left(\frac{\partial p}{\partial x} \right)$$

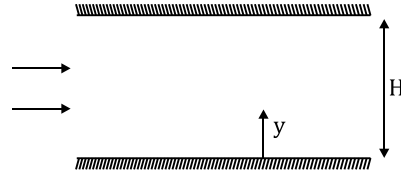
$$(B) u = -\frac{1}{4\mu} \left(\frac{\partial p}{\partial x} \right) [R^2 - r^2]$$

$$(C) u_{\max} = \frac{1}{4\mu} \left(-\frac{\partial p}{\partial x} \right) (R^2)$$

$$(D) V_{\text{avg}} = \frac{V_{\max}}{2}$$

2. **Laminar Flow Through Two Parallel Plate:**

Case A:



$$\tau = -\frac{\partial p}{\partial x} \left(\frac{H}{2} - y \right)$$

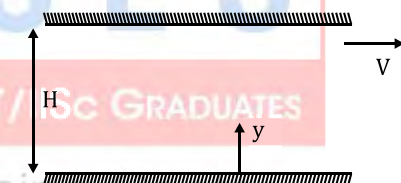
$$\tau_{\text{wall}} = -\frac{\partial p}{\partial x} \left(\frac{H}{2} \right)$$

$$u = \frac{1}{2\mu} \left(\frac{\partial p}{\partial x} \right) (Hy - y^2)$$

$$u_{\max} = -\frac{1}{8\mu} \left(\frac{\partial p}{\partial x} \right) (H^2)$$

$$u_{\text{avg}} = \frac{2V_{\max}}{3}$$

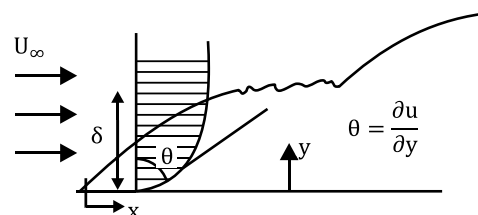
Case B: (couette flow)



$$u = -\frac{1}{2\mu} \left(\frac{\partial p}{\partial x} \right) [Hy - y^2] + \frac{Vy}{H}$$

BOUNDARY LAYER THEORY:

Boundary layer region is highly viscous and rotational region of flow $\Rightarrow$ so Bernoulli's equation not applicable.



Boundary Condition:

at $x = 0, \delta = 0$

at $y = 0, u = 0$

at $y = \delta, \frac{\partial u}{\partial y} = 0$

at $y = 0, \frac{\partial^2 u}{\partial y^2} = 0$

$\Rightarrow \delta^*$ [Displacement thickness]

$$= \int_0^\delta \left(1 - \frac{U}{U_\infty}\right) dy$$

Loss of mass flow rate $= (\rho \delta^* U_\infty \cdot b)$

b = Width of plate

Momentum Thickness $[\theta]$

$$\theta = \int_0^\delta \frac{U}{U_\infty} \left(1 - \frac{U}{U_\infty}\right) dy$$

$F_{\text{drag}} = \rho A U_\infty^2 \Rightarrow \rho(\theta \times b) \times U_\infty^2$

Energy Thickness $[\delta^{}]$**

$$= \int_0^\infty \frac{U}{U_\infty} \left(1 - \left(\frac{U}{U_\infty}\right)^2\right) dy$$

Shape Factor $= \frac{\delta^*}{\theta}$

$\delta > \delta^* > \delta^{**} > \theta$ valid for all velocity profile.

Von Karman Momentum Integral Equation.

$$\frac{\tau_o}{\rho U_\infty^2} = \frac{d\theta}{dx} \quad \text{Valid for laminar and turbulent}$$

Used when velocity profile given in the problem.

$$T_o = \mu \left(\frac{\partial u}{\partial y} \right)_{y=0}$$

Blasius Equation: (Used when velocity profile is not given)

Laminar Flow:

$(Re < 5 \times 10^5)$

$$\delta = \frac{5x}{\sqrt{Re_x}}$$

$$C_D = \frac{1.328}{\sqrt{Re_L}}$$

$$CF_x = \frac{0.664}{\sqrt{Re_x}}$$

Re = Reynold's Number

C_D = Average drag coefficient.

CF_x = Local Drag Coefficient.

$$\delta^* = \frac{1.72(x)}{\sqrt{Re_x}}$$

$$\theta = \frac{0.664(x)}{\sqrt{Re_x}}$$

Turbulent Flow: (Used when 1/7th law given in problem) $\frac{u}{U_\infty} = \left(\frac{y}{\delta}\right)^{1/7}$

$$\delta = \frac{0.16x}{(Re)^{1/7}}$$

$$\delta^* = \frac{0.02(x)}{(Re)^{1/7}}$$

$$\theta = \frac{0.016(x)}{(Re)^{1/7}}$$

Boundary Layer Separation:

$$\left. \frac{\partial u}{\partial y} \right|_{y=0} = 0 \text{ and } \frac{\partial p}{\partial x} > 0$$

■ DIMENSIONAL ANALYSIS

Dynamic Similarity:

$$\frac{F_{\text{inertia}})_m}{F_{\text{inertia}})_p} = \frac{F_{\text{viscous}})_m}{F_{\text{viscous}})_p}$$

$$\left(\frac{F_i}{F_v}\right)_m = \left(\frac{F_i}{F_v}\right)_p$$

$$Re)_m = Re)_p$$

Reynold's number for model and prototype shall be same.

$$F_{\text{inertia}} = \rho L^2 V^2$$

$$F_{\text{viscous}} = \mu V L,$$

where μ = Viscosity



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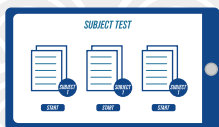
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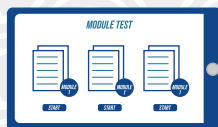
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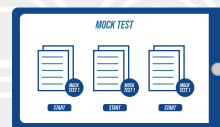
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